ToMato: Token Merging 가 Vision Transformer

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ToMato: Accelerating ViT via Token Merging

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Abstract

ViT(Vision Transformer) shows outstanding performance in various vision tasks by splitting images into patches and passing them through transformer blocks. However, the large model size and computational cost of ViT result in high inference latency and hindered acceleration. To accelerate ViT efficiently, we introduce **ToMato(Token Merging at Once)**, a simple framework that recursively merges tokens by comparing similarity to adjacent tokens at the first transformer block. Applying the ToMato to DeiT-base model, we find that this reduces latency by 22.19% while maintaining high Top-1 accuracy of 80.14%. Our codes are available at <https://github.com/Transformer04/ToMato>.

I.

Model	Top-1 Accuracy	Latency Reduction
ViT(Vision Transformer)	80.14%	-
ToMato	80.14%	22.19%
DeiT-base	80.82%	-

2. ToMato ImageNet -mini
ToMato ToMe

```

function: visit_recursive
Input: similarity threshold sim, attention score similarity attn, token index idx, visited tokens visited
if idx not in visited then
  visited.add(idx)
  if each 4 adjacent tokens(idx±1, idx±14) attn >= sim then
    visit_recursive()
  end if
end if
    
```

15%

ToMato
22.19%, 6.06%

DeiT -base Top-1
0.82%, 0.59%

Top-5
0.40%, 0.31%

ToMe 가

DeiT 가

1. ToMato
DeiT -base, ToMe

Model	Top-1 acc (%)	Top-5 acc (%)	Latency (s)
DeiT-B	80.96	95.40	13.2132
ToMe-B	80.73	95.31	10.9445
OURS-B	80.14	95.00	10.2804

ToMato sim 가

3 r ToMe sim

ToMato Top-1

ToMe

ToMato 가

3. ToMe, ToMato

token merging ViT

ToMato(Token Merging at transformer block)

가

Once)

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